

# robotex

International

## MINI SUMO RULES

COMPETITION COORDINATOR

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## **1 Introduction**

This document defines the rules for the robots of Mini Sumo. The rules are based on the Baltic Robot Sumo Rules.

## **2 Robot classes**

Only autonomous robots are represented at the Sumo competition of Robotex in the following classes:

1. Mini Sumo;

## **3 The Competition**

### **3.1 Definition**

One operator and two assistants can be registered for every robot (3 team members in total). However, only the operator is allowed to guide the robot. Both contestants must follow the competition rules, the terms and conditions of winning and participate using only self-made autonomous robots at the Dohyo area designated beforehand. The winner is announced by the judges.

### **3.2 Format**

The competition format is established by the tournament organisers, depending on the number of participants. If the number of participants is high, sub-groups will be used in order to decide who enters the final tournament. The finals are held in the format of double-elimination tournament. If the number of participants is low, all contestants will immediately compete in the format of final tournament.

### **3.3 Sub-classes**

Robotex Mini Sumo competitions take place in single age group.

## 4 Dohyo Jyonai

Dohyo Jyonai (the match ring area) consists of the Dohyo (the match circle) and the Yochi (the outer layer area of Dohyo). The rest of the space will be deemed as area Dohyo Jyogai (outside the Dohyo area).

The Dohyo (the match circle) is a circle that is covered with a black colour coating.

Table 1 Parameters of the Sumo fields

Class	Height	Diameter	Court material
Mini Sumo	1 - 5 cm	77 cm	wood/plastic

### 4.1 Starting cross

The starting cross is placed in the middle of the Sumo field and it divides the field into four equal sectors. The robots must always be located in two reciprocal sectors (see Figure 1). The robot must cover the area of Tawara (white line) at least partially. The referee removes the starting cross from the field once the robots have been placed.

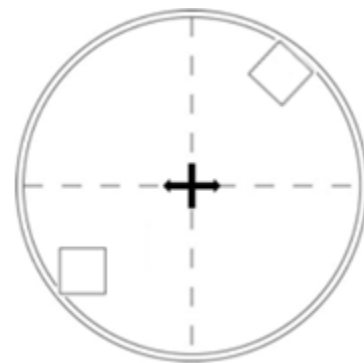


Figure 1 Starting cross

The robot cannot be moved after it has been placed on the field.

### 4.2 Tawara (white line).

Tawara is the white line around the Dohyo. Tawara line is a part of the Dohyo.

Table 2 Dimensions of Tawara by competition classes

Class	Width of Tawara
Mini Sumo	2.5 cm

### 4.3 Yochi

Yochi is an area around the Dohyo with a diameter of at least 100 cm for Mini Sumo. Yochi colour and material can be freely chosen from all colours besides white.

## 5 The Robot

### 5.1 Requirements for the robot

#### 5.1.1 Dimension and weight restrictions

Table 3 Dimension and weight restrictions

Class	Mass	Length*	Width *	Height
Mini Sumo	0.5 kg	10 cm	10 cm	unlimited

\* NB! Start Module must be placed on top of the robot on the highest point of the robot, not on the side or under the robot.

\* The robot may expand after the start of the round but must stay in one piece.

#### 5.1.2 Autonomous robots – starting the movements

Table 4 Starting the movements

Class	Starting method
Mini Sumo	Official infrared remote control operated by the referee. See the technical specification of the compulsory receiving device from Appendix 2. Start and stop remote control system.

#### 5.1.3 Autonomous robots – stopping the movements

Table 5 Stopping the movements

Class	Stopping method
Mini Sumo	The referee stops the robots by using official infrared remote control. See the technical specification of the compulsory receiving device from Appendix 2. Start and stop remote control system. Additionally, the operators of the robot can use their remote controls to stop the robot.

#### 5.1.4 Requirements for blade use

- It is not forbidden to use double blades.
- It is forbidden to use any components that may separate from the robot when it moves or comes into contact with another robot.
- For Mini Sumo robots, all edges, including but not limited to the front scoop, must not be sharp enough to damage the ring (exception is when the robots collide), other robots, or players.

## 5.2 Movements of autonomous robots

The movements of the robot should be designed to detect the movements of the opponent and respond/attack accordingly. If there is any doubt in the autonomy of the robot, the referees have the right to inspect the control logic of the robot.

## 5.3 Use of remote control devices with autonomous robots

During the competition (round), the remote control devices must be placed on a previously designated area. The devices may only be used to stop the robot, when the referee gives a corresponding command. The official infrared remote control device is held by the referee.

## 5.4 Prohibited components of the robot

1. Any components that may disturb the operation of the opponent (for example, flashlights or jamming devices such as IR LEDs intended to saturate the opponents IR sensors).
2. Any components that may damage or scratch the surface of Dohyo. An exception is when the robots collide.
3. Any components that are designed to damage the opponent.
4. It is forbidden to use any liquids, powders and gas as a weapon against the opponent.
5. It is not allowed to use any inflammable materials in the robot.
6. The robot must not include any throwing devices (for example throwing a net on opponent).
7. The robot must not include any parts, which fix it onto the Dohyo (for example, glues, suction cups, ventilators for suction purposes etc.).

## 6 Match principles

1. The match generally contains three rounds and lasts up to three minutes. The team who will be first to earn two Yuko points (effective points) during the time of the match, will be the winner. Match time is measured during rounds, not between them.
2. If only one Yuko point has been earned by the end of the match time, the winner is the team who earned it.



3. If neither team wins any rounds during the match time, the winner will be announced according to the situation of Yusei (dominance), see paragraph 8.3. If Yusei cannot be decided or the number of rounds that has been won is the same for both teams, the match time will be extended by three minutes. If one team earns one or more Yuko points during the extended time, then this team will be the winner.
4. The contestants have a maximum of 30 seconds between the rounds to maintain their robot.

## 7 Organizing the competition

### 7.1 Safety requirements

For safety purposes, the referees and contestant must wear gloves and goggles according to the robot class.

Table 6 Safety requirements

Class	Gloves	Goggles
Mini Sumo	required	not required

### 7.2 Starting the match

The match starts with the referee's signal. The contestants will bow to each other before they enter the area of Dohyo Jyonai.

Before each round and with the signal from the referee, the contestants place their robots simultaneously on the Dohyo. The robots must be placed in reciprocal sectors and at least some part of the robot must stay on the white line (see Figure 1 Starting cross). The robots are not allowed to move after they have been placed on the Dohyo.

The round begins with a method that has been described for each robot class.

Table 7 Start method

Class	Starting method
Mini Sumo	The participants leave the area of Dohyo Jyonai after they have placed their robots there. The referee starts the round by sending a start command via official infrared remote control. The robots may start moving after they have received the start command.

In case the Dohyo area is scratched or becomes dirty, the referees decide whether to continue the match on the same Dohyo or replace it.



### 7.3 Ending the match

1. The referee gives a signal to end the match and stop the robots. The stopping method is separately designated for each class.

Table 8 Stopping method

Class	Stopping method
Mini Sumo	The referee stops the robots by sending a stop command via official infrared remote control. Additionally, the operators of the robots can use their own methods to stop the robot.

2. The match ends officially after a corresponding signal from the referee. The participants must take their robot from the Dohyo, bow to each other and leave the area of Dohyo Jyonai.

### 7.4 Torinaoshi (repeat of the round)

The round is repeated in the following situations.

1. Both robots are facing each other, and their movement is hindered, or they do not move at all.
2. Both robots fall out of the Dohyo at the same time.
3. Other situations in which it is not possible to determine who has won or lost.
4. If it is not possible to announce the winner after Torinaoshi, the referee may place the robots himself or herself and continue with the match within the allocated time.

### 7.5 Handling the robots between the matches

For the time between the matches in the same sub-group, the robots must be placed on a table assigned for it and can only be removed from there for the duration of the match. It is forbidden to leave the competition area with the robot between the matches, except for when a corresponding permission has been given (e.g. the robot needs fixing). During the sub-group tournament, it is not allowed to modify the robot. The purpose of this requirement is to guarantee a smooth course of the competition.

**NB! If the robot cannot be found from the designated table at the right time or if the team itself is not present, the match will result in a loss.**

## 8 Yuko (effective) point, Shinitai and Yusei (dominance)

### 8.1 Yuko (effective) point

The winner is announced in the following situations.

1. If the opponent has been pushed out of the Dohyo (the robot touches the area outside of the Dohyo).
2. If the opponent falls out of the Dohyo and touches the area outside of the Dohyo.
3. In the situation of "Shinitai".
4. In the situation of "Yusei (dominance)".
5. If "Keikoku (warning)" is given twice to the opponent.
6. If there is a case of "Hansoku (violation)".
7. If the winner is announced without a match, the winner earns two Yuko points (if the winner already has one Yuko point, he or she earns only one more). The existing Yuko point(s) of the opponent who lost remain effective.

### 8.2 Shinitai

"Shinitai" situation means that one or several wheels of the robot roll out of the Dohyo and the robot is unable to return to the Dohyo. In this case, the opponent earns one Yuko point.

### 8.3 Yusei (dominance)

In a situation of "Yusei" (dominance), the referee may grant a Yuko point to the team according to the strategy, movements and skills of the robot.

## 9 Hansoku (violation) and penalty

### 9.1 Keikoku (warning)

A contestant who acts as indicated below gets a "Keikoku" (warning). If the contestant gets two Keikokus (warnings), the opponent earns one Yuko point.

1. If the operator or some item of the operator (for example, remote control) ends up in the area of Dohyo Jyonai before the round ending signal of the referee.
2. If the robot moves before the beginning of the round (movement or changing its shape).
3. If the participant violates the requirements for the use of remote control.
4. If the robot is replaced after it is placed on the Dohyo.
5. If the participant does not comply with the safety requirements.

6. In case of any other action that is considered unfair.

## **9.2 Hansoku (violation)**

In the following situations the opponent or both parties earn one Yuko point.

1. If some parts, with total weight of more than 5 grams fall off from the robot.
2. If the robot does not move.
3. If both robots move, but do not collide.
4. If the robot is on fire or a situation, which resembles that the robot is on fire.
5. If the participant wants to end the round.

## **9.3 Hansokumake (defeat due to violation)**

The participant who violates the following rules, loses the match due to violation.

1. If the contestant fails to show up at the designated Dohyo at the beginning of the match or the participant exceeds the time given for maintenance, see paragraph 6 Match principles.
2. If the contestant sabotages the match. For example, by deliberately breaking or deforming the Dohyo.
3. If the participant violates the requirements provided for "The Robot" in paragraph 5. If the robot does not make autonomous movements.
4. If the participant does not comply with the requirements provided in paragraph 7.1 Safety requirements, even after paragraph 9.1 "Keikoku" (warning).

## **9.4 Sikkaku (disqualification)**

In the following cases, the participant will be disqualified – he or she must leave the competition and is not added to the list of competition results.

1. If the participant's robot does not comply with the requirements provided in paragraph 5. The Robot.
2. If the participant behaves in an undignified manner. For example, swears or offends the opponent or the referees.
3. If the participant deliberately injures the opponent.

## 10 Suspending the match

1. If the participant is injured and the match cannot be continued, the participant may demand the suspension of the match.
2. In the event of the previously described situation, the referees make necessary arrangements for the match to be immediately resumed.
3. If the arrangements do not enable the match to continue, the opponent wins the competition without a match.

## 11 Objections

The decisions of the referees are not subject to appeals. Complaints must be submitted during or immediately after the match. If no settlement is reached with the referee, claims must be submitted immediately to the Robotex Head referee. Any later complaints will not be accepted. In case of any conflicts or disputes, the final word will be said by the referees and/or the organisers. **NB! Rude behaviour is not tolerated and the team who does not respect the referee's / head referee's decisions can be disqualified by the head referee and/or event organisers.**

## 12 Marking the robots

### 12.1 Markings on the robot

The robots must be marked with number stickers (robot number). The stickers are provided by the organisers of the competition. The sticker cannot be placed on the plow of the robot, or on any other component, where it may disturb the work of opponent's sensors.

## 13 Changes and cancellations in the rules

Changes and cancellations made to the rules are adopted by the main organiser of the competition according to the regulation of the regulatory committee of the competition.

## 14 Appendix 1. Figure of match area

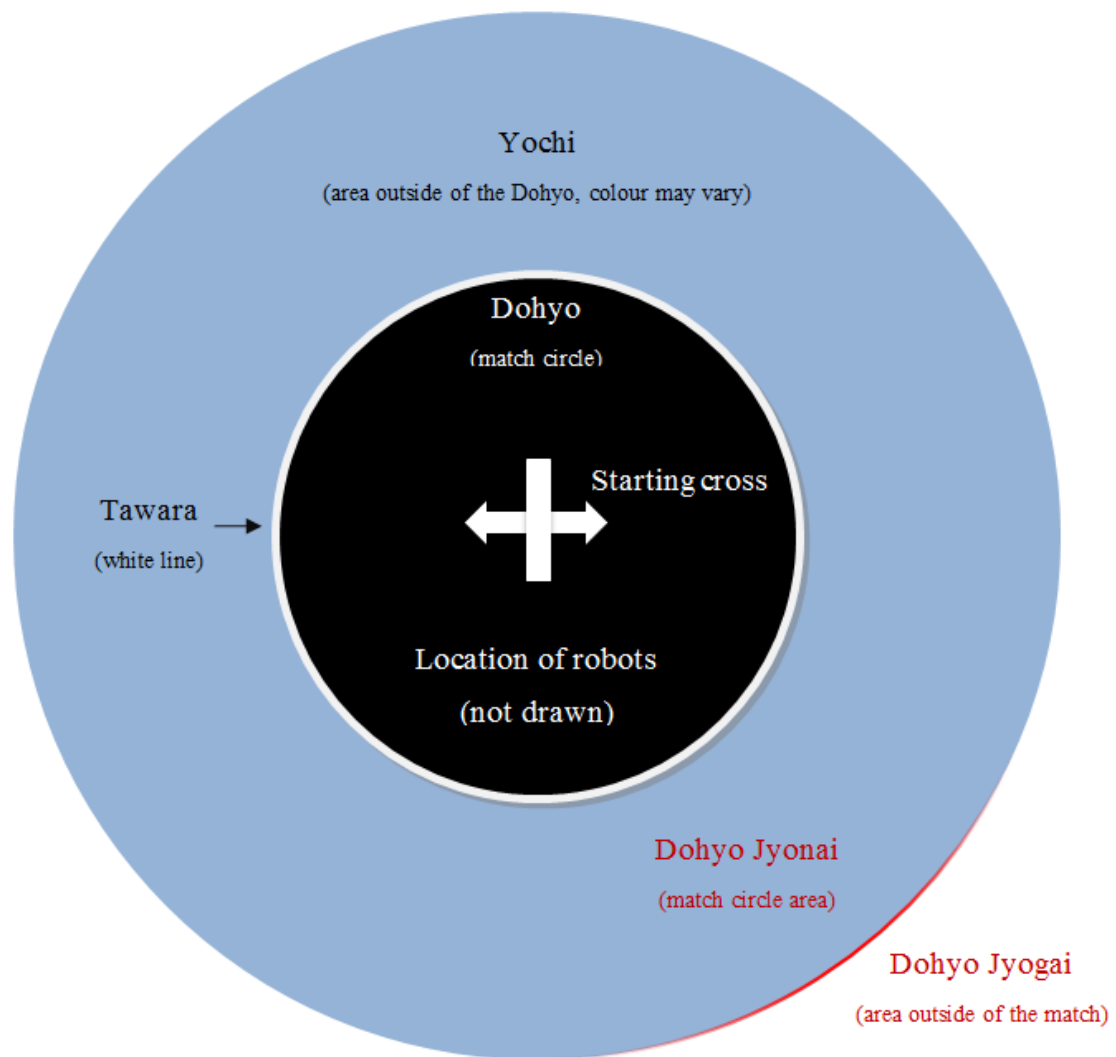


Figure 2 Match area

## 15 Appendix 2. Start and stop remote control system

The same start and stop remote control system applies to Robotex Sumo as used in the competitions of MRC Global Robot Olympiad, Robolympics and IEEE Robowars (JSumo MicroStart Start Module). The aim of the system is to ensure fair and quick start of the round. Using one and the same control system in different competitions is convenient for the participants.

The system is based on the Digital IR remote, which is operated by the referee, and on Digital IR receiver module, which are located on top of the robots. The module receiving signals on 38 khz and is based on Sony Sirc protocol at 38 khz, so module works with any type of Sony remotes.

Start Module is equipped with 2 LEDs.

- RED LED – indicates stop signal.
- BLUE LED – indicates start signal.

The MicroStart Start Module configuration for competition.

- START SIGNAL – When signal output goes from 0V to 5V [Logic 1]
- STOP SIGNAL – When signal output goes from 5V to 0V [Logic 0]

The functioning of the mentioned signals will be tested during the technical inspection of the robot.

**More information and JSumo MicroStart Start Module can be found here:**

<https://www.jsumo.com/microstart-sumo-minisumo-robot-start-module>

**Datasheet of the module:**

<https://jsumo.com/Data/EditorFiles/additional/microstart-eng.pdf>

**Test video of MicroStart Module for easier understanding:**

<https://www.youtube.com/watch?v=J1liSEkVleA>

**For better and secure signal for the Start Module, manufacturer recommend sealing the module side area, 3D print of the case for the Module can be found here: ("Microstart Case") <https://www.jsumo.com/3d>**



## 16 Revision history

1. 15.06.2024 Removed previous rule change history before 2020
2. 15.06.2024 Paragraph 11. Added disqualification option for rude behavior.
3. 15.06.2024 Paragraph 15. Appendix 2. Added new description about new Start Module.
4. 15.06.2024 Paragraph 12.1. Specified marking on the robot.
5. 15.06.2024 Paragraph 5.4. Part 7. Added example and prohibited the use of ventilators for suction purposes.
6. 15.06.2024 The layout and form of the document have been cleaned up.
7. 15.06.2024 Removed Micro Sumo category.

